LOW TEMPERATURE RANGE SMARTMOTOR™ (SM17205M-LTR)

Engineered for robust and reliable operation in harsh environments and high altitudes



The Moog Animatics Low Temperature Range (LTR) SmartMotor™ is available in a standard NEMA 17 frame size, model SM17205M-LTR (the "LTR-17"). This motor has been engineered for robust and reliable operation in extremely frigid environments and at high altitudes. $^{[1]}$

To achieve this, onboard internal heaters ensure that the motors can start up in temperatures below -40 degrees C. Along with this, other design changes allow these motors to withstand random vibrations up to 6 G RMS, 10 - $2000\,Hz$, and standard IP sealing protects the motors from condensation. $^{[2]}$

The LTR-17 motor allows you to have SmartMotor™ capability in a fully integrated, IP sealed package specifically designed for extremely low temperature and high altitude applications.

Features:

- NEMA 17 size
- Designed for operation with extreme temperatures, vibrations and high altitude
- IP62 high altitude operation
- Low temp startup with onboard heater to raise circuit temperature from -65 to -40 $^{\circ}\text{C}$
- Magnetic, single turn absolute encoder
- Four 5 V TTL sourcing inputs
- RS-422 differential communication
- FAA approved, click-fit connector
- Non-RoHS

 $^{[1]}$ For RoHS exempt applications only – the LTR motors contain lead-based solder on some internal components to achieve increased reliability over greater thermal ranges.

[2] IP sealed only when mounted to an equivalently sealed mating component.

ADVANTAGES

- Extreme low temperature startup through onboard heater
- Protection against condensation through standard IP sealing
- High altitude operation ensured through proprietary design and testing
- Ease of programming through powerful AniBasic (BASIC-like) language with over 200 commands
- Minimal cabling and space requirements due to fully integrated design
- Ability to solve difficult application problems through field-proven Class 5 features

APPLICATIONS

- Aerospace motion actuation where high altitude and low temperature are factors
- Motion requirements in arctic regions
- Pan and tilt solar collectors
- High altitude surveillance cameras
- Refrigerated food and pharmaceutical processing
- Wind tunnel testing in extreme temperatures
- Cryogenic containment handling
- Cold thermal test chambers
- Nozzle/valve flow for coolers
- Ice handling systems



SPECIFICATIONS

TECHNICAL DATA

	36	oz-in
Continuous torque (up to 4500 rpm)	0.25	N-m
Book to an act of all	66	oz-in
Peak torque at stall	.47	N-m
Nominal continuous power (@ 5500 rpm)	135	watts
No load speed	7,200	rpm
Motor constant	7.3	oz-in/(watts) ^{.5}
Rotor inertia	21.7	(oz-in-sec²) x10 ⁻⁴
Weight	0.6	lb
	0.27	kg
Shaft diameter	0.20	in
	5.08	mm
Shaft, radial load	7	lb
	3.17	kg
Shaft, axial thrust load	1.36	lb kg
Maximum continuous current (@ 6000 rpm)	3.6	amps
Peak power (@ 5100 rpm)	155	watts
Torque sensitivity (K _t)	8.8	oz-in/amp
Voltage constant (K _e)	6.51	volts/krpm
Terminal resistance (R _T)	1.44	7 1
Terminal inductance (L₁)	1.4	mH

Storage temperature -65 to +85 °C.

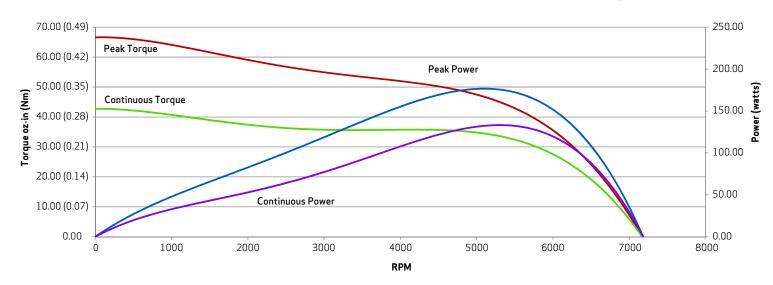
Normal operating temperature -55 to +70 °C.

External power or heater must bring temperature up to at least -40 $^{\circ}$ C for startup from cold.*

Warning: This product contains lead-based solder on some internal components.

PERFORMANCE TORQUE AND POWER CURVE

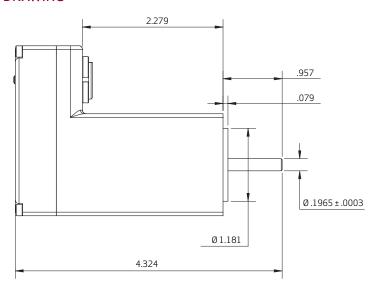
SM17205M-LTR motor torque versus speed, 48 volts, MDT commutation, 25 °C ambient (curves are derated at higher ambient).

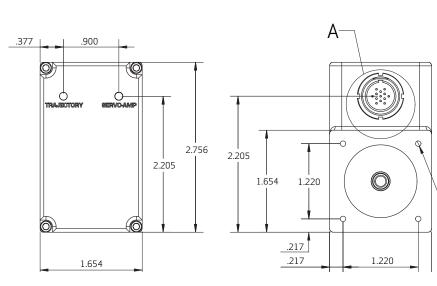




^{*}Consult manual found on the website for more details.

OUTLINE DRAWING





CONNECTORS

Pin	Signal	
1	+48V motor power in	
2	Motor power return (common)	9 2 8 1 1 7 12 12 12 12 Detail A
3	Rx-	
4	Heater power return	
5	+48V heater power in	
6	General purpose I/O 2	
7	General purpose I/O 1	
8	General purpose I/O 0	
9	Rx+	
10	Tx+	
11	I/O power return (common)	
12	General purpose I/O 3	
13	Tx-	

Motor connector is Glenair® model 804-005-07M8-13PA.

4X 4-40 UNC-2B √.315

Dimensions are in inches

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For product information, visit

www.animatics.com

This technical data is based on current available information and is subject to change at any time. Specifications for specific systems or applications may vary.

